Smart Objects & Ambient Intelligence - Invited Speakers

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Smart Objects & Ambient Intelligence October 12th - 14th 2005, Grenoble, FRAN(

Invited speakers

Emile AARTS - "Ambient Intelligence : Visualising the Future" (Philips Research Laboratories Eindhoven - The Netherlands) Hans GELLERSEN - "Cooperative Systems of Physical Objects" (Computing Department at Lancaster University - UK)

Alex WAIBEL - "CHIL Computing to Overcome Techno-Clutter" (Carnegie Mellon University, Pittsburgh and University of Karlsruhe - Germany)

Emile AARTS 🕇



Prof.dr. Emile Aarts is Vice President and Scientific Prograr the Philips Research Laboratories Eindhoven, The Netherla an MSc. and PhD. degree in physics. For almost twenty yea been active as a research scientist in computing science. Si holds a teaching position at the Eindhoven University of Tec part-time professor of computing science. He also serves or scientific and governmental advisory boards. He holds a pai of senior consultant with the Center for Quantitative Method Eindhoven, The Netherlands. Emile Aarts is the author of fiv more than hundred and forty scientific papers on a diversity including nuclear physics, VLSI design, combinatorial optim neural networks. In 1998 he launched the concept of Ambie and in 2001 he founded Philips' HomeLab. His current resei include embedded systems and interaction technology.

Abstract of the intervention : "Ambient Intelligence : Visualisinç Future"

Ambient Intelligence systems are aimed at making usersystem interaction and cor consumption a truly positive experience. The endless search for nifty information v mechanism to squeeze yet one more piece of information onto a visual display is : the challenge to embed interactive displays into our environments that bring true u experience. Examples of experiences supported by immersiveness, social intellige freedom have been investigated in the Philips HomeLab. HomeLab offers an uniq environment for evaluating the feasibility and usability of technologies that are use realisation of Ambient Intelligent scenarios. Equipped with an extensive observatic infrastructure of 34 cameras and microphones, the HomeLab has enabled behavior researchers to study the effect of innovative technologies on the user's acceptanc Intelligence. In the presentation we discuss recent developments resulting from ou HomeLab with an emphasis on the relation between (information) visualization an

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http://www.soc-eusai2005.org/sneaker.php

Hans GELLERSEN 🕈



Hans Gellersen is a professor of interactive systems in the Department at Lancaster University. His research interest i computing and embedded interactive systems. This spans enabling technologies such as position and context sensing interfaces beyond the desktop, and embedding of intelliger everyday artefacts. Hans has led a number of European cc on these topics, and he is a principal investigator in major i including the Equator project in the UK. He is participating Ubiquitous Computing research community, founded the H conference series, and recently served as program co-cha 2005.

Hans has been a full professor at Lancaster since 2001. Pr was a researcher at the University of Karlsruhe. He holds ϵ PhD in Computer Science, both from Karlsruhe.

Abstract of the intervention : "Cooperative Systems of Physical

Notions of 'smart objects' often conjure up images of everyday items that begin to fantastic life of their own. In contrast, physical objects that are beginning to be inte deployed in computational infrastructures typically have little or no autonomy as co objects. They reside at the periphery of such systems, and may be able to locally through sensors and actuators while being reliant on backend infrastructure to pro observed and to decide what is actuated. In this talk we consider systems of phys that are more autonomous and independent of infrastructure but no less focussed deployment and application. The systems we think of are decentralized (all compu embedded in the physical objects), highly contextualized (physical objects have a and affordance), and variable in configuration (resulting from physical use and mo objects). The individual objects in such systems are naturally limited in the extent can interact with the world : how they are manipulated and configured is dependent physically afford and support, and what they sense and affect is inherently local. T challenge we explore is how physical objects can form cooperative systems capat interactions with their environment. The specific challenges we consider include h cooperate to model activity and assess situations in their environment, how object establish their spatial configuration through cooperative sensing, and how we may interfaces that exploit ad hoc composition of physical interface components.

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Alex WAIBEL 1

Alex Waibel is a Professor of Computer Science at Carnegic University, Pittsburgh and at the University of Karlsruhe (Ge directs the Interactive Systems Laboratories (www.is.cs.cmu. Universities with research emphasis in speech recognition, I recognition, language processing, speech translation, mach

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and multimodal and multimedia interfaces. At Carnegie Mell serves as Associate Director of the Language Technology II Director of the Language Technology PhD program. He was founding member of the CMU's Human Computer Interactio (HCII) and continues on its core faculty. Dr. Waibel was one founders of C-STAR, the international consortium for speech research and served as its chairman from 1998-2000. His te developed the JANUS speech translation system, the JANU: recognition toolkit, and a number of multimodal systems incl Genoa Meeting recognizer and meeting browser.

Abstract of the intervention : "CHIL Computing to Overcome Te Clutter"

After building computers that paid no intention to communicating with humans, we recent years developed ever more sophisticated interfaces that put the "human in computers. These interfaces have improved usability by providing more appealing (graphics, animations), more easy to use input methods (mouse, pointing, clicking and more natural interaction modes (speech, vision, gesture, etc.). Yet the produc have been promised have largely not been seen and human-machine interaction spartially frustrating and tedious experience, full of technoclutter and excessive atter by the technical artifact.

In this talk, I will argue, that we must transition to a third paradigm of computer use let people interact with people, and move the machine into the background to obsihumans' activities and to provide services implicitly, that is, -to the extent possible explicit request. Putting the "Computer in the Human Interaction Loop" (CHIL), ins other way round, however, brings formidable technical challenges. The machine n always observe and understand humans, model their activities, their interaction itt humans, the human state as well as the state of the space they are in, and finally, intentions and needs. From a perceptual user interface point of view, we must pro from sensors that are always on, frequently inappropriately positioned, and subjec greater variablity. We must also not only recognize WHAT was seen or said in a g but also a broad range of additional information, such as the WHO, WHERE, HOV WHY, WHEN of human interaction and engagement.

In this talk, I will describe a variety of multimodal interface technologies that we hat to answer these questions and some preliminary CHIL type services that take adv perceptual interfaces.

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